

ARM Exam EN0-001

ARM Accredited Engineer

Version: 6.0

[Total Questions: 210]



Question No: 1

A deeply embedded real-time industrial control system is missing some hard real-time interrupt deadlines. Which of the following performance analysis techniques is the most suitable for identifying which routines are causing the problem?

- **A.** Use an ETM instruction trace profiler, which outputs information about the program as it runs
- **B.** Add some serial logging to the software, which outputs information about the program as it runs
- **C.** Add a new interrupt handler, which is triggered off a timer, and dump information about the interrupted process
- **D.** Use a JTAG sample-based profiler, which periodically halts the CPU, and dumps information about the interrupted process

Answer: A

Question No: 2

In a multi-processor system, there are four processors numbered 0, 1, 2 and 3. The state of the processors is as follows:

CPU 2 executes a SEV instruction. What is the effect on the system?

- A. CPU 0: executing, CPU 1: executing, CPU 2: executing. CPU 3: executing
- B. CPU 0: executing, CPU 1: executing. CPU 2: executing. CPU 3: sleeping
- C. CPU 0: sleeping, CPU 1: sleeping. CPU 2: executing. CPU 3: executing
- D. CPU 0: sleeping, CPU 1: sleeping. CPU 2: sleeping, CPU 3: executing

Answer: C

Question No: 3

Consider the following instruction sequence:

STR r0, [r2]; instruction A



DSB

ADD r0, r1, r2; instruction B

LDR r3, [r4]; instruction C

SUB r5, r6, #3; instruction D

At what point will execution pause until the STR access is complete?

- A. After instruction A and before the DSB
- B. After the DSB and before instruction B
- C. After instruction B and before instruction C
- D. After instruction C and before instruction D

Answer: B

Question No: 4

A simple method of measuring the performance of an application is to record the execution time using the clock on the wall or a wristwatch.

When is this method INAPPROPRIATE?

- A. When executing the software using a simulation model
- B. When the processor is a Cortex-R4
- **C.** When instruction tracing is enabled
- **D.** When the processor is not executing instructions from cache

Answer: A

Question No: 5

When a linker is removing unused sections during a static link (for example, -remove or -gc-sections), it finds the sections to keep by following all relocations starting from:

- **A.** The entry point(s).
- **B.** The function named 'main'.
- **C.** All local functions and variables.



D. The reset vector.

Answer: A

Question No: 6

In which of these cases would code have better performance when compiled for Thumb state than when compiled for ARM state?

- A. When the processor has no data cache
- **B.** When the code involves many shifting operations
- C. When the code has many conditionally executed instructions
- **D.** When the processor can only fetch instructions 16-bits at a time

Answer: D

Question No:7

When using a Generic Interrupt Controller (GIC), how does code cause a softwaregenerated interrupt?

- A. By executing an SGI instruction
- **B.** By writing to a register in the GIC
- C. By writing to the F bit in the CPSR
- **D.** By writing to the I bit in the CPSR

Answer: B

Question No:8

Processors which implement the ARMv7-A architecture can be configured to allow unaligned memory access. Unaligned accesses have a number of advantages, disadvantages, and limitations.

Which TWO of the following statements are true? (Choose two)

A. Unaligned accesses may take more cycles to execute than aligned accesses



- B. Unaligned loads and stores are necessary for accessing fields in packed structures
- **C.** A program compiled using unaligned accesses can be safely executed on all ARMv7-A devices
- **D.** If the relevant control register setting is enabled all loads and stores can function from unaligned addresses
- E. Unaligned accesses can only be made to Normal memory

Answer: A,E

Question No:9

Which of the following instructions can be used to enter a power saving mode?

- A. PLD
- B. PLI
- C. WFE
- D. DSB

Answer: C

Question No: 10

According to the AAPCS (with soft floating point linkage), when the caller "func" calls sprintf, where is the value of the parameter "x" placed?

```
#include <stdio.h>
void func(double x, int i , char *buffer)
{
sprintf(buffer, "pass %d: value = %f\n", i, x); }
```

- A. Split between register R3 and 4 bytes on the stack
- B. Split between registers R3 and R4
- C. 8 bytes on the stack
- D. VFP Register D0

Answer: C



Question No: 11

When timing a critical function for an algorithm, using platform time functions such as get time of day (), the result is unpredictable; there is significant variance in the measured time between different runs of the benchmark. Which of the following strategies would improve the accuracy of the measurement?

- **A.** Time multiple executions of the algorithm and average the result
- **B.** Break the algorithm into smaller pieces and time them individually
- C. Run the code on a software model of the platform and collect the results on that system
- **D.** Add some code with a known overhead to the algorithm to make it run slower, and remove the overhead afterwards

Answer: A

Question No: 12

How many bytes of stack are needed to pass parameters when calling the following function?

int foo(short arg_a, long long arg_b, char arg_c, int arg_d)

- **A.** 0
- **B**. 4
- **C**. 8
- **D.** 15

Answer: C

Question No: 13

Which instruction would be used to return from a Reset exception?

- A. MOVS PC, R14
- B. MOVSPC, R13



- C. Architecturally not defined
- **D.** SUBS PC, R14, #4

Answer: C

Question No: 14

On an ARM processor that does not implement Security Extensions, which one of the following can be the starting address of the exception vector table?

- A. 0xFFFFFFF
- **B.** 0xFFFFFF0
- **C.** 0xFFFF0000
- **D.** 0x0000FFFF

Answer: C

Question No: 15

In the Generic Interrupt Controller (GIC), when an interrupt is requested, but is not yet being handled, it is in which of the following states?

- A. Inactive
- B. Active
- C. Pending
- D. Edge-triggered

Answer: C

Question No: 16

An undefined instruction will cause an Undefined Instruction exception to be taken when:

- A. It is fetched.
- **B.** It is decoded.
- C. It is executed.
- **D.** It writes back its results.



Answer: C

Question No: 17

The following pseudocode sequence shows a flag being set to indicate that new data is ready to be read by another thread:

data = 123;

ready = true;

Assuming that the reader threads may execute on any other core of a multicore system, which of the following is the most efficient memory barrier to place between the two writes to prevent them being observed in the opposite order?

- A. DSBSY
- B. DSBST
- C. DMBSY
- D. DMBST

Answer: D

Question No: 18

Which one of the following statements is TRUE for monitor mode debugging?

- **A.** Monitor mode debug might be suitable for debugging timing critical control software
- **B.** Monitor mode debug only supports hardware breakpoints and watchpoints
- C. Monitor mode debug can be used to halt instruction execution on the processor
- **D.** Monitor mode debug is only available for ARM processors with a JTAG debug port

Answer: A

Question No: 19

A Programmer's View CPU model usually provides:



- **A.** Cycle-accurate simulation of the CPU.
- **B.** Instruction-accurate simulation of the CPU.
- C. Simulation of user-defined memory-mapped peripherals.
- **D.** Cycle-accurate simulation of the cache and memory system.

Answer: B

Question No: 20

In an ARMv7-A processor that includes the Advanced SIMD extension (NEON), where are the data values operated on by NEON instructions stored?

- A. In system memory
- B. In registers shared with the VFP register set
- C. In registers shared with the integer register set
- **D.** In dedicated registers not shared with other registers

Answer: B

Question No: 21

The following C function is compiled with hard floating point linkage.

float function(int a, float b, int c, float d);

Which register is used to pass argument c?

- **A.** R0
- **B.** R1
- **C.** R2
- **D.** R3

Answer: B

Question No: 22

Which one of the following statements best describes the function of vector catch logic?

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- **A.** It traps writes to the memory containing the vector table
- B. It provides additional resources for debugging exception handlers
- C. It provides configurable exception priorities on an ARM processor
- **D.** It provides an improved mechanism for an application to handle exceptions

Answer: B

Question No: 23

The automatic removal of a cache line from a cache to free the location is known as cache line:

- A. Coherency
- B. Pre-fetch
- C. Eviction
- D. Allocation

Answer: C

Question No: 24

In the CPSR, 1=0 and F=1. Which of the following is TRUE in this case?

- A. Both IRQs and FIQs are enabled
- B. Both IRQs and FIQs are disabled
- C. IRQs are disabled and FIQs are enabled
- D. IRQs are enabled and FIQs are disabled

Answer: D

Question No: 25

Which of the following statements regarding Strongly-ordered memory is architecturally FALSE?

- A. Address locations marked as Strongly-ordered memory are never held in a cache
- B. The architecture does not permit speculative data accesses to Strongly-ordered memory